**OpenCV:**

1. Display the location of the ball from the base position using OpenCV + ROS (using RGB image)

2. Display the location of the ball from the base position using OpenCV + ROS (using depth image)

Reference: pyimagesearch.com

docs.opencv.org

**Prepare a word document in to include the following:**

* Aim
* Methods (Write about the procedure followed, commands used)
* Python program
* Screen shot of your result